

Optimizing Control of Chemical Plants under Uncertain Parameters: a Multiobjective Optimization Approach^{*}

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Abstract. This paragraph shall summarize the contents of the paper in short terms. XXXXXXXXXXX XXXXXX cccccc XXXXXXXXXXX ccc XXXXX.

Keywords: optimal control, nonlinear system, dynamic programming.

1. Introduction

XXXXXXXXXX (Bellman, 1957) XXXXXX ... the explanation of the background work¹, the practical applications and the nature and purpose of the paper ... XXXXXX cccc (Tarantello, 1982a, b) XXXX ccc (Maschler and Peleg, 1976) XXXXXXX.

2. This is a First-Order Title

2.1. This is a Second-Order Title

Consider an optimal control problem (OCP) with dynamics ... XXXXXXX cccccc.

Definition 1. A Borelian function $H: [0, T] \times \mathbb{R}^{2n} \rightarrow \mathbb{R}$ is called (A_∞, B_∞) -subquadratic at infinity if there exists a function $N(t, x)$ such that ...

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This is a Third-Order Title. We shall first consider the question of nontriviality ... XXXXXXX cccccc XXXXXXXXXXX ccc XXXXX cccccc XXXXXXX c XXXXX cccccc XXXXXXXXXXX.

Theorem 1 (Ghoussoub-Preiss). Assume $H(t, x)$ is $(0, \varepsilon)$ -subquadratic at infinity for all $\varepsilon > 0$, and T -periodic in t ...

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^{*} This work was supported by the French Foundation for Fundamental Researches under grants No.99-01-00146 and 96-15-96245.

¹ See XXXXXXXXXXX cccccccccc

This is a Fourth-Order Title. We assume that H is (A_∞, B_∞) -subquadratic at infinity ... ccccc xxxxxxxx ccccccc xxxx.

Lemma 1. Assume that H is C^2 on $\mathbb{R}^{2n} \setminus \{0\}$ and that $H''(x)$ is non-degenerate for any $x \neq 0$. Then any local minimizer \tilde{x} of ψ has minimal period T .

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Proposition 1. Assume $H'(0) = 0$ and $H(0) = 0$. Set:

$$\delta := \liminf_{x \rightarrow 0} 2N(x) \|x\|^{-2} \quad . \tag{1}$$

If $\gamma < -\lambda < \delta$, the solution \overline{u} is non-zero:

$$\overline{x}(t) \neq 0 \quad \forall t \; . \tag{2}$$

Proof (of proposition). Condition (1) means that

It is an exercise in convex analysis, into which we shall On the other hand, we check directly that □

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Corollary 1. Assume H is C^2 and (a_∞, b_∞) -subquadratic at infinity. Let ...

Xxxxxx ccccccc ... Proposition 1 tells us that ... xxxxxx ccccc xxxxxxxxxxx ccccccc xxxx ccccc xxxxxxxx ccccccc xxxxxx xxxxxx.

2.2. This is a Second-Order Title again

The first results on subharmonics were ... xxxxxx ccccccc xxxxxx xxxxxxx ccccccc xxxx cc xxxxxxxxxxxxxx ccccc xxxxxxxx.

Fig. 1. This is the caption of the figure displaying a white eagle and a white horse on a snow field.

Table 1. This is the example table.

Year	World population
8000 B.C.	5,000,000
50 A.D.	200,000,000
1650 A.D.	500,000,000
1945 A.D.	2,300,000,000
1980 A.D.	4,400,000,000

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Remark 1. The results in this section are a refined version of

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cccccccccc xxxxx.

Example 1 (External forcing). Consider the system:

$$\dot{x} = JH'(x) + f(t) \quad (3)$$

where the Hamiltonian H is . . . xxxxxx ccccccccc xxxxxxx ccc xxxxxxxxxxxxxx.

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3. Conclusion

XXXXXXXXXXXX ccccccccc xxxxxxx ccc xxxxxxxxxxxxxx (Clarke et al., 1980) xxxxx cc-
ccccccc. XXXXXXXXXXX ccccccc . . . by Subbotina (1986) . . . cccc xxxxx ccc xxxxxxxxxxx.

Acknowledgments. The authors express their gratitude to R. J. Brown for useful discussions on the subjects.

Appendix

1. First Appendix

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2. Second Appendix

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